



# **Combined Modeling of Eco-Signal Operations Applications**

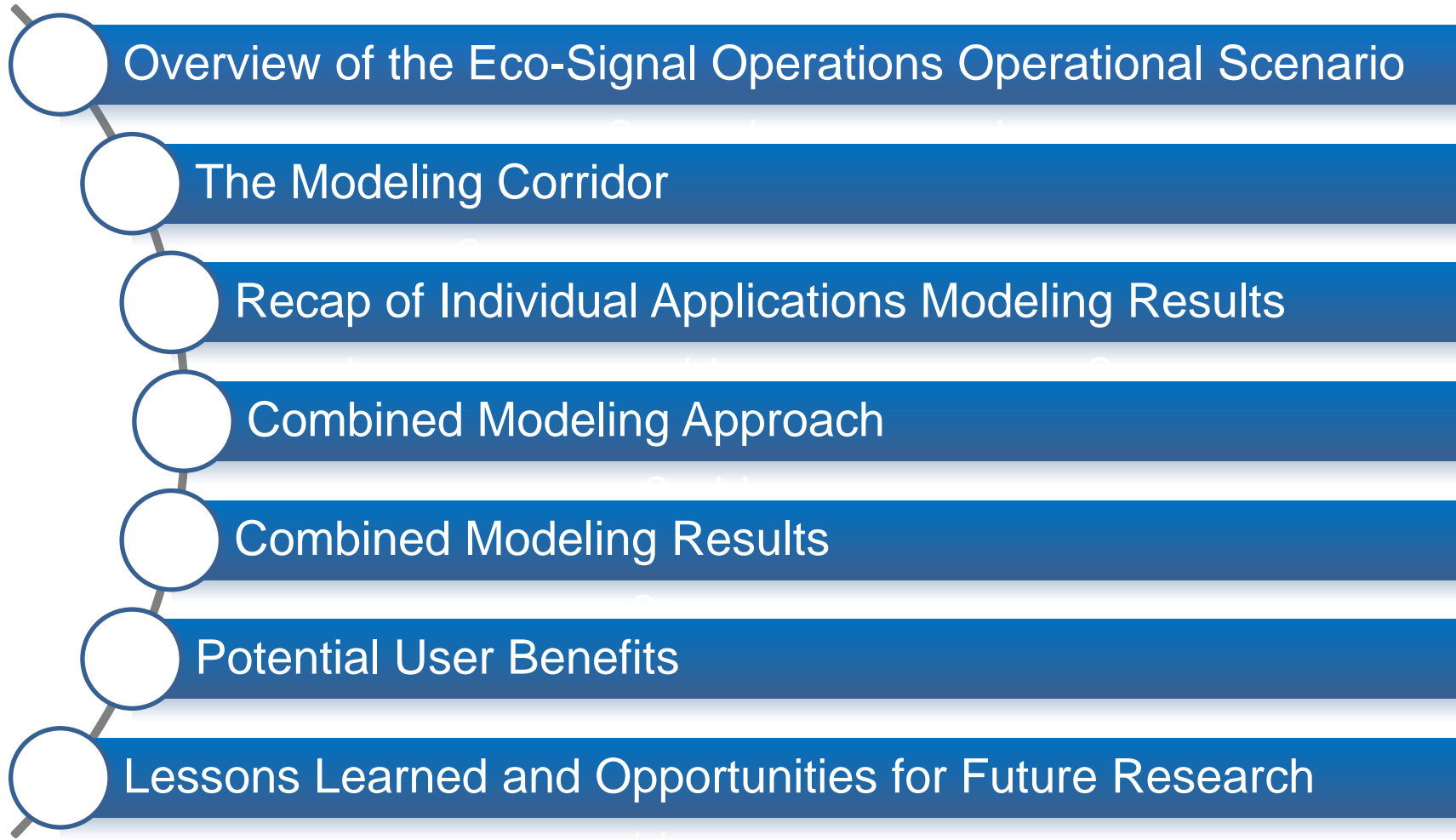
**Applications for the Environment: Real-Time Information  
Synthesis (AERIS) Program**

Summer Webinar Series

June 25th, 2014

# Presentation Overview

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# Overview of the Eco-Signal Operations Operational Scenario

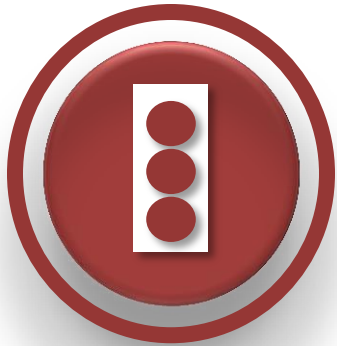
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- The **Eco-Signal Operations Operational Scenario** uses connected vehicle technologies and applications, as well as signal operational communications technologies, to reduce fuel consumption, greenhouse gas (GHG) and criteria air pollutant emissions on signalized arterial roadways
- The scenario consists of five individual applications, modeled **individually** with modeling results presented in the **AERIS Fall/Winter Webinar Series (November 2013 – March 2014)**
  - *Past webinars can be found at <http://www.its.dot.gov/aeris/>*
- Upon completion of the individual application modeling and analysis, the applications were **modeled together** to investigate the potential benefits of deploying integrated connected vehicle applications along a signalized corridor



# Eco-Signal Operations Applications

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## ECO-SIGNAL OPERATIONS

- Eco-Approach and Departure at Signalized Intersections
- Eco-Traffic Signal Timing
- Eco-Traffic Signal Priority
  - Eco-Transit Signal Priority
  - Eco-Freight Signal Priority
- Connected Eco-Driving
- *Wireless Inductive/Resonance Charging (not modeled)*



# Overview of the Eco-Signal Operations Operational Scenario

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**The combined modeling of the Eco-Signal Operations applications sought to answer the following questions:**

- *What technical challenges would there be in combining the individual applications?*
- *Would the results of the applications be additive, or would one application nullify or conflict with another?*
- *Do all of the applications affect the same environmental measures, or are they different?*
- *In what conditions do the applications shine, and which do they falter?*



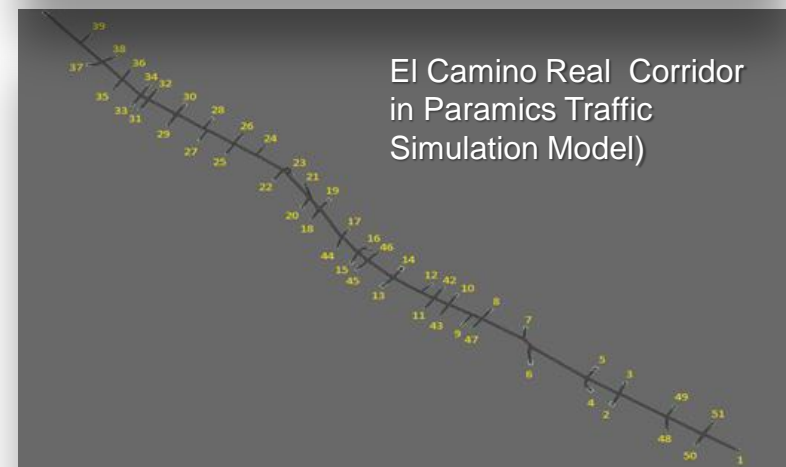
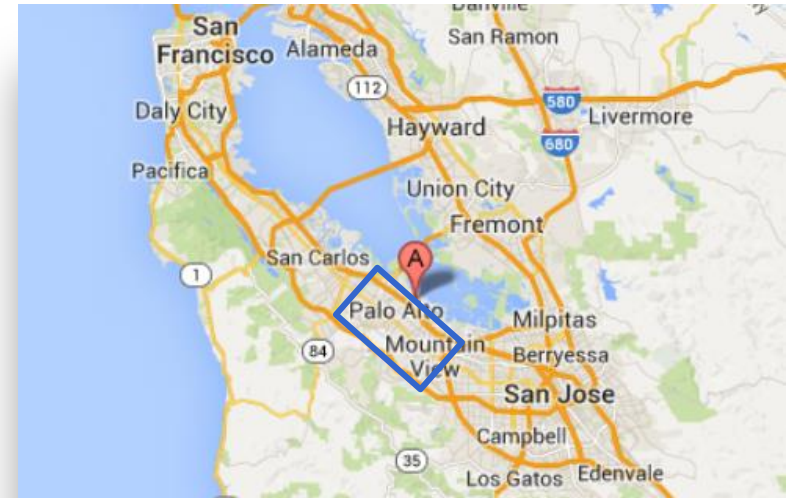
# The Modeling Corridor

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# Modeling Corridor: El Camino Real

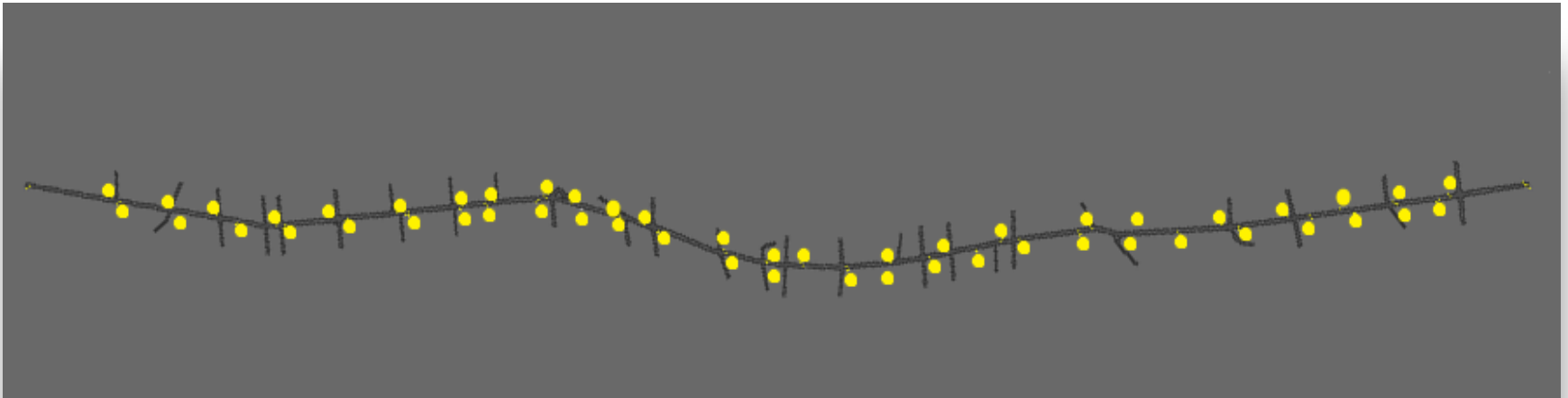
- A real-world corridor was chosen for analysis and modeling
- El Camino Real is a major north-south arterial connecting San Francisco and San Jose, CA
- The modeling corridor consisted of:
  - A six-mile segment of El Camino Real (using 2005 network and demand conditions)
  - Three lanes in each direction for the majority of the corridor with a 40 mph speed limit
  - 27 signalized intersections that were well coordinated / optimized
  - Intersection spacing that varied from 650 to 1,600 feet



# Region of Modeling: El Camino Real in Northern California

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- 1.2% freight demand in baseline model
- Mainline transit routes in both directions along the El Camino Real:
  - 10 minute headways between buses (6 per hour)
  - 27 bus stops in each direction, near signalized intersections (includes near-side and far-side stops)





# Modeling Corridor: El Camino Real in Northern California

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- Detailed simulation modeling was conducted under different **traffic conditions, network conditions, connected vehicle penetration rates**, and other variables
- Simulation parameters (e.g., car-following logic, lane-change behavior) were **calibrated** using NGSIM data sets
- Many of the applications were initially modeled on a 3-intersection model as a **proof-of-concept** to test the algorithm
- After the initial tests, the application was modeled on the full corridor model of El Camino Real
- Individual modeling was completed first and then individual models were modeled collectively in a single model for **combined** analysis



# Recap of Individual Applications Modeling Results

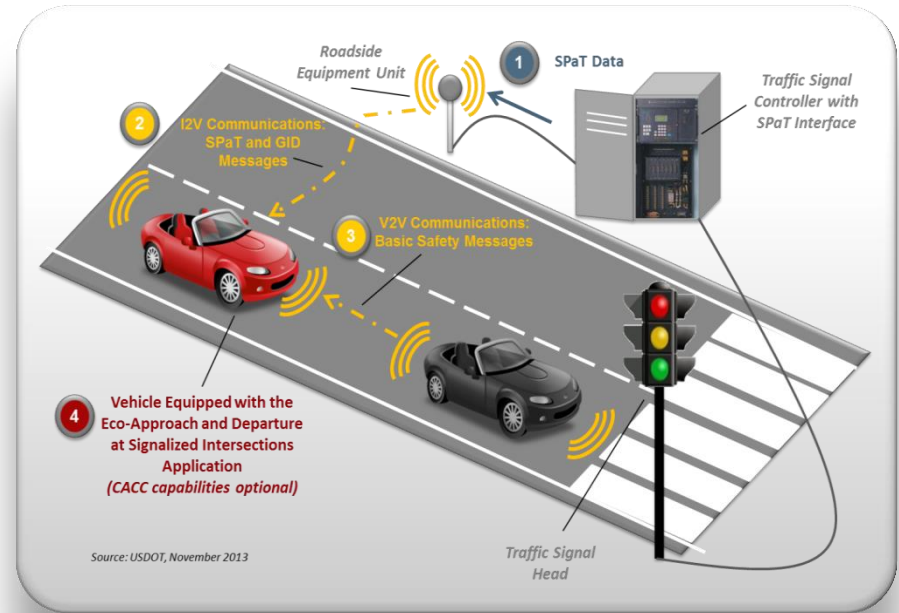
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# Eco-Approach and Departure at Signalized Intersections Application

## Application Overview

- Collects signal phase and timing (SPaT) and Geographic Information Description (GID) messages using vehicle-to-infrastructure (V2I) communications
- Collects basic safety messages (BSMs) from nearby vehicles using vehicle-to-vehicle (V2V) communications
- Receives V2I and V2V messages, the application performs calculations to determine the vehicle's optimal speed to pass the next traffic signal on a green light or to decelerate to a stop in the most eco-friendly manner
- Provides speed recommendations to the driver using a human-machine interface or sent directly to the vehicle's longitudinal control system to support partial automation



# Eco-Approach and Departure at Signalized Intersections Application: Modeling Results

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## ▪ Summary of Preliminary Modeling Results

- 5-10% fuel reduction benefits for an uncoordinated corridor
- Up to 13% fuel reduction benefits for a coordinated corridor
  - 8% of the benefit is attributable to signal coordination
  - 5% attributable to the application

## ▪ Key Findings and Takeaways

- The application is less effective with increased congestion
- Close spacing of intersections resulted in spillback at intersections. As a result, fuel reduction benefits were decreased somewhat dramatically.
- Preliminary analysis indicates significant improvements with partial automation
- Results showed that non-equipped vehicles also receive a benefit – a vehicle can only travel as fast as the car in front of it

## ▪ Opportunities for Additional Research

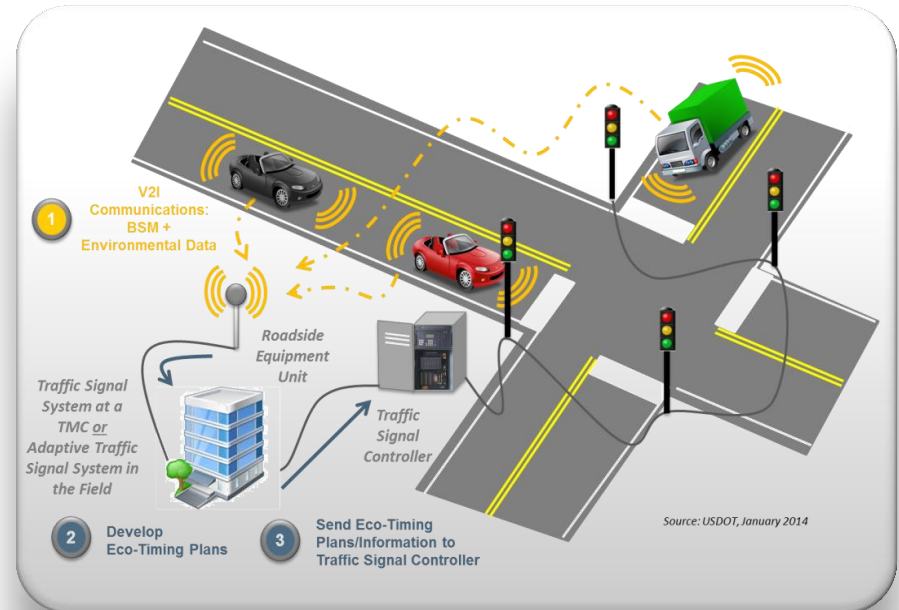
- Evaluate the benefits of enhancing the application with partial automation



# Eco-Traffic Signal Timing Application

## Application Overview

- Similar to current traffic signal systems; however the application's objective is to optimize the performance of traffic signals for the environment
- Collects data from vehicles, such as vehicle location, speed, vehicle type, and emissions data using connected vehicle technologies
- Processes these data to develop signal timing strategies focused on reducing fuel consumption and overall emissions at the intersection, along a corridor, or for a region
- Evaluates traffic and environmental parameters at each intersection in real-time and adapts the timing plans accordingly



# Eco-Traffic Signal Timing Application: Modeling Results

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## ▪ Summary of Preliminary Modeling Results

- Up to 5% fuel reduction benefits at full connected vehicle penetration
  - 5% fuel reduction benefits when optimizing for the environment (e.g., CO<sub>2</sub>)
  - 2% fuel reduction benefits when optimizing for mobility (e.g., delay)

## ▪ Key Findings and Takeaways

- Optimization of signal timings using environmental measures of effectiveness resulted in mobility benefits in addition to environmental benefits
- For the El Camino corridor, modeling results indicated that shorter cycle lengths (60 seconds) produce greater benefits than longer cycle lengths (130 seconds)

## ▪ Opportunities for Additional Research

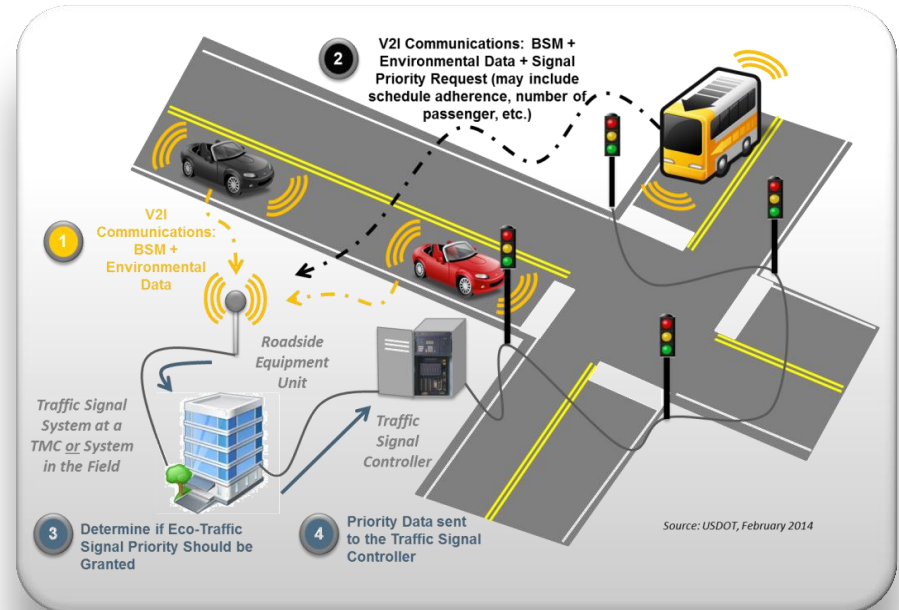
- Consider analysis for different geometries (e.g., grid network) and traffic demands (e.g., a corridor with higher volumes on the side streets)
- Investigate adaptive or real-time traffic signal timing optimization algorithms



# Eco-Traffic Signal Priority Application

## Application Overview

- Allows either transit or freight vehicles approaching a signalized intersection to request signal priority
- Considers the vehicle's location, speed, vehicle type (e.g., alternative fuel vehicles), and associated emissions to determine whether priority should be granted
- Information collected from vehicles approaching the intersection, such as a transit vehicle's adherence to its schedule, the number of passengers on the transit vehicle, or weight of a truck may also be considered in granting priority
- If priority is granted, the traffic signal would hold the green on the approach until the transit or freight vehicle clears the intersection



# Eco-Traffic Signal Priority Application: Modeling Results

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## ▪ Summary of Preliminary Modeling Results

- Eco-Transit Signal Priority provides up to 2% fuel reduction benefits for transit vehicles → Up to \$669,000 annual savings for fleet of 1,000 transit vehicles driving 44,600 miles each on arterials a year; larger fleet of 3,000 vehicles → \$2M
- Eco-Freight Signal Priority provides up to 4% fuel reduction benefits for freight vehicles → Up to \$649,000 annual savings for fleet of 1,000 city delivery vehicles driving 30,000 miles on arterials each year; large fleet of 80,000 vehicles → \$51M

## ▪ Key Findings and Takeaways

- Eco-Transit Signal Priority
  - Reduced emissions for buses; however in some cases, signal priority was detrimental to the overall network
  - Provided greater overall environmental benefits when the bus' adherence to its schedule was considered by the algorithm
- Eco-Freight Signal Priority
  - Passenger vehicles and unequipped freight vehicles also saw reductions in emissions and fuel consumption, benefiting from the additional green time

## ▪ Opportunities for Additional Research

- Investigate advanced algorithms that collect data from all vehicles and evaluate impacts of granting priority in real-time

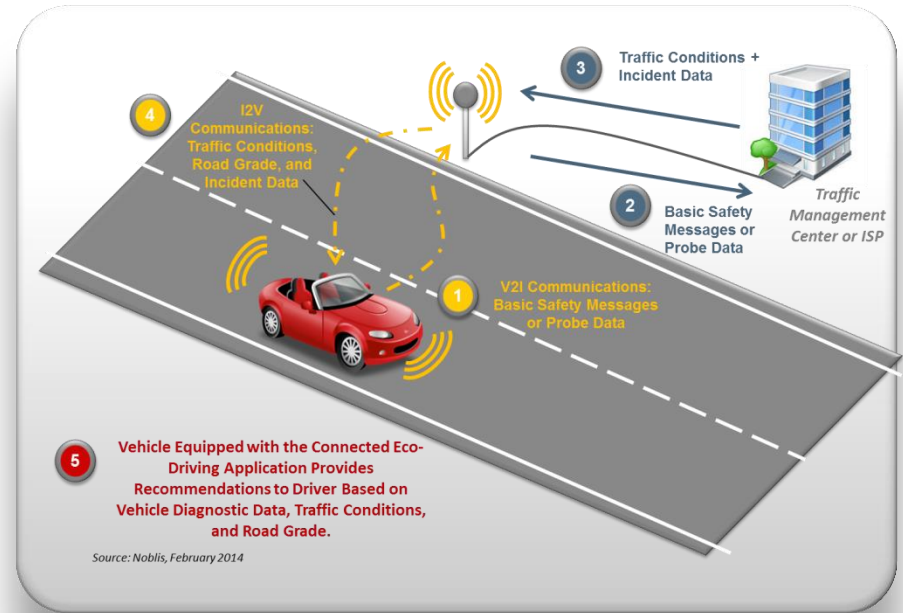




# Connected Eco-Driving Application

## Application Overview

- Connected Eco-Driving provides customized real-time driving advice so drivers can adjust their driving behavior to save fuel and reduce emissions.
- Driving advice includes recommended driving speeds, optimal acceleration, and optimal deceleration profiles
- Receives V2I and V2V messages, the application determines the vehicle's optimal acceleration and deceleration profiles to navigate the corridor in the most eco-friendly manner
- Provides these recommendations to the driver using a human-machine interface or sent directly to the vehicle's longitudinal control system to support partial automation



# Connected Eco-Driving Application: Modeling Results

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- **Summary of Preliminary Modeling Results**

- Up to 2% fuel reduction benefits at full connected vehicle penetration
- Up to 2% dis-benefit in mobility due to smoother and slower accelerations to meet environmental optimums

- **Key Findings and Takeaways**

- The application is much more amenable to different levels of congestion than the other Eco-Signal Operations applications
- Results showed that non-equipped vehicles also receive a benefit – a vehicle can only travel as fast as the car in front of it

- **Opportunities for Additional Research**

- The decision module could be further improved, taking into account the real-time information of the preceding vehicle
- Automated longitudinal control could be integrated to further improve compliance with the speed, acceleration, and decelerations
- Future research could consider could consider roadway grade and downstream traffic conditions, which were not modeled



# Combined Modeling Approach

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# Modifications to Support Combined Modeling

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- To successfully integrate the modules for combined modeling, the following actions were implemented:
  - The Eco-Traffic Signal Timing genetic algorithm (GA) was run before the modeling as the new signal timing plan for which the other four applications run in combination
  - The Eco-Transit Signal Priority and the Eco-Freight Signal Priority application APIs were combined to form a “combined” priority application
  - A new API was developed to track priority requests from both freight and transit vehicles
  - An additional module developed to handle “conflicting” priority requests



# Combined Modeling of Applications as Implemented in Simulation

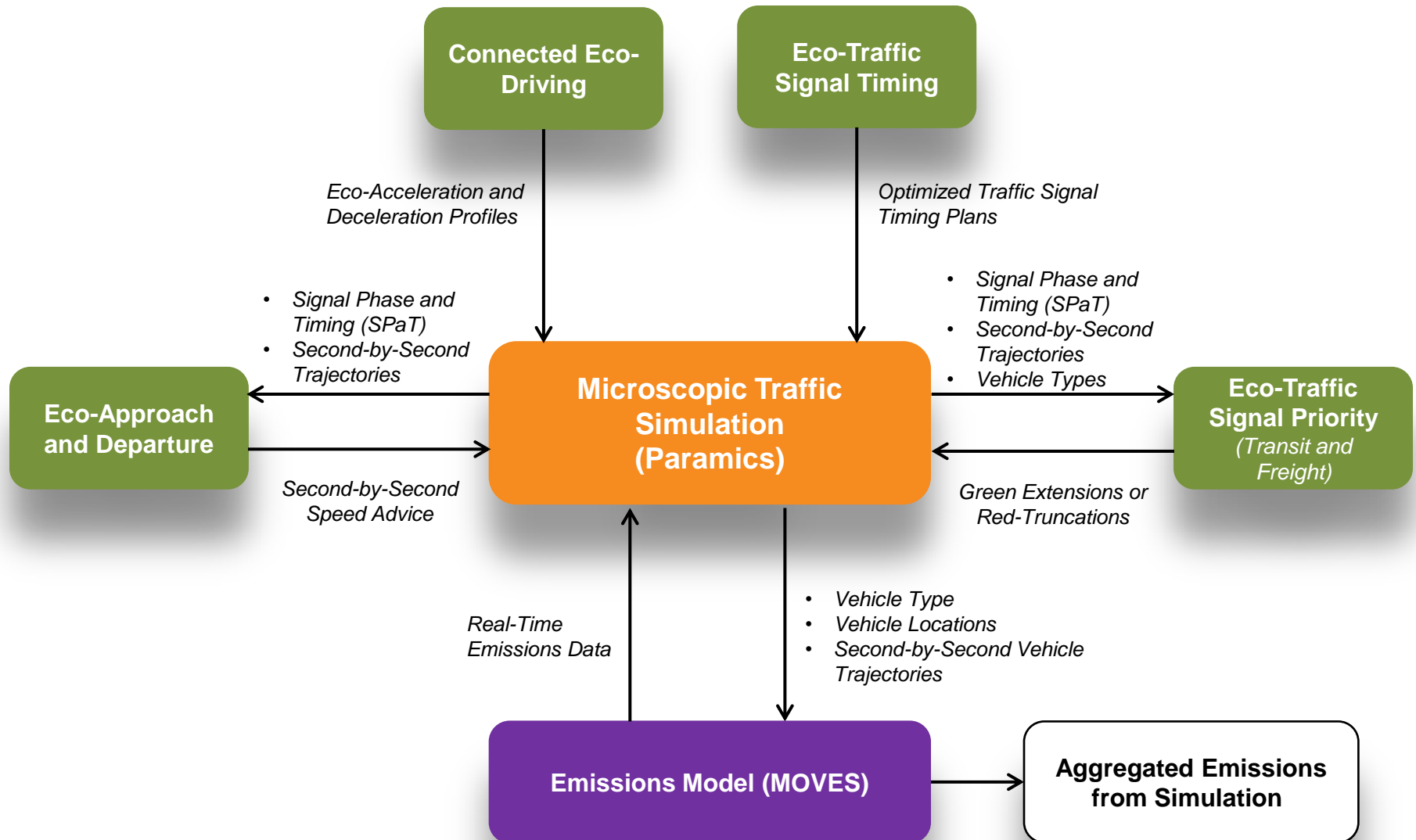
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To model the Eco-Signal Operations applications, there were three vital components:

- **Microscopic Traffic Simulation**: in order to test the priority algorithm in simulated conditions in real-time, **Paramics** micro simulation program was used
- **Eco-Signal Operations Application APIs**: the individual original and modified **Paramics APIs** for the 5 applications were implemented, which simulated connected vehicle technology
- **Emissions Model**: the environmental modeling program **MOVES** was coded as an API to use with Paramics that provided real-time emissions from the simulation



# Combined Modeling Approach

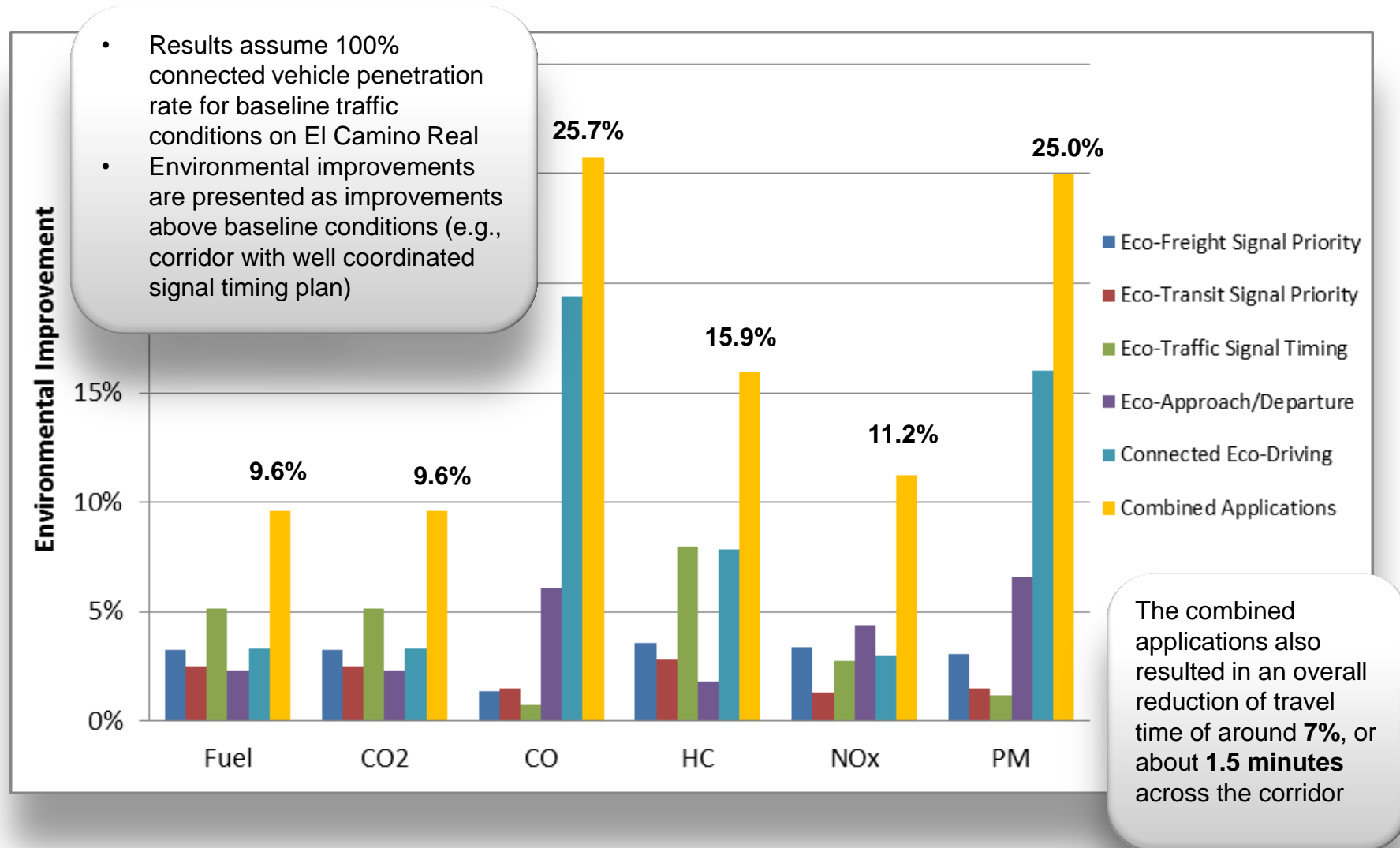


# Combined Modeling Results

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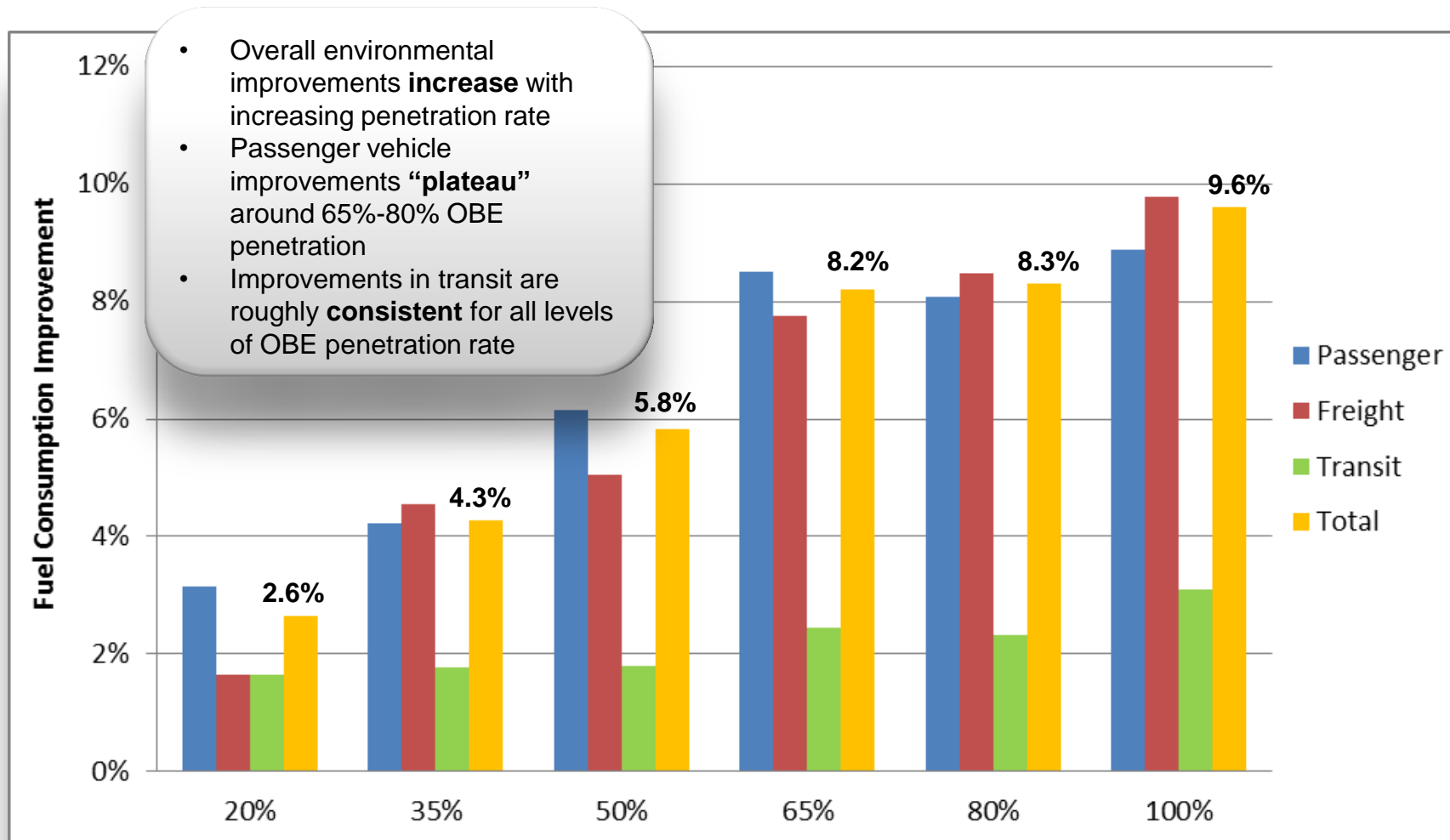


# Environmental Impacts of Combined Applications



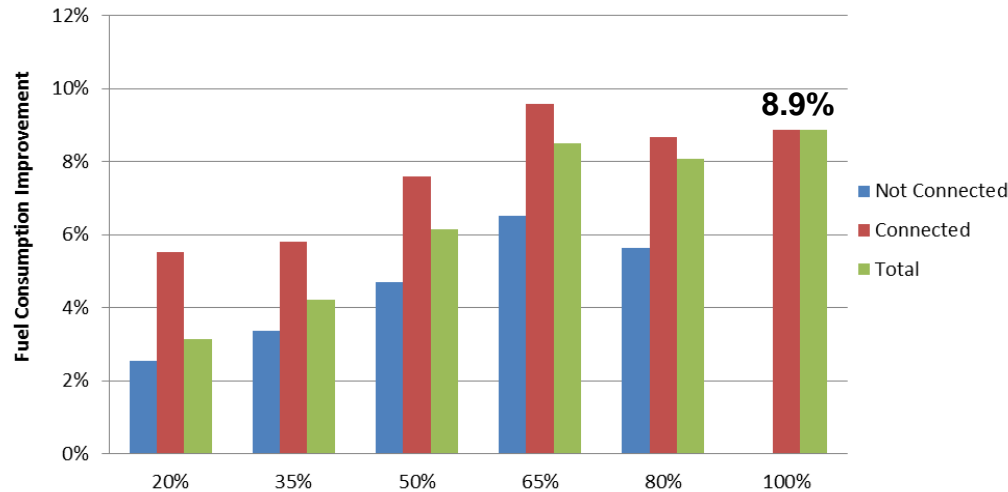


# Impact on the Environment due to Increasing OBE Penetration Rates

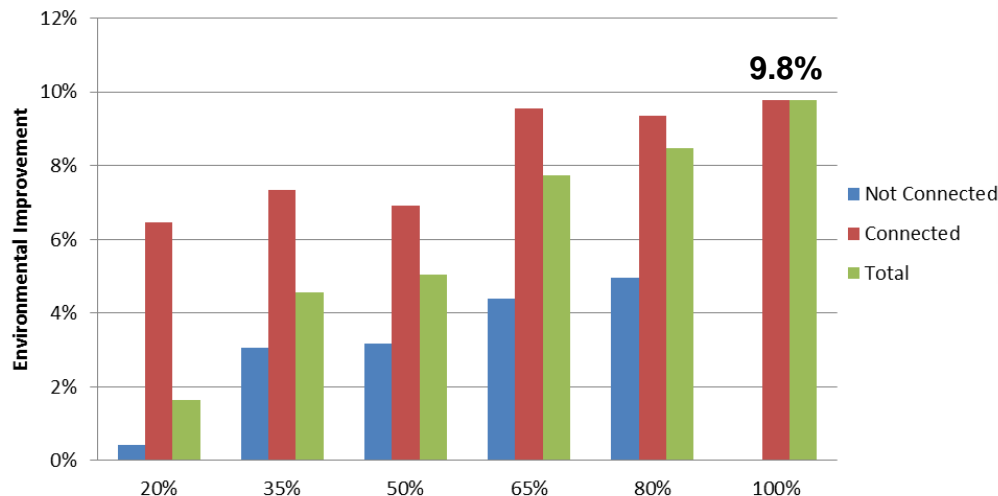


# Secondary Impacts for Non-Connected Vehicles

Passenger Improvements - Connected vs. Not-Connected



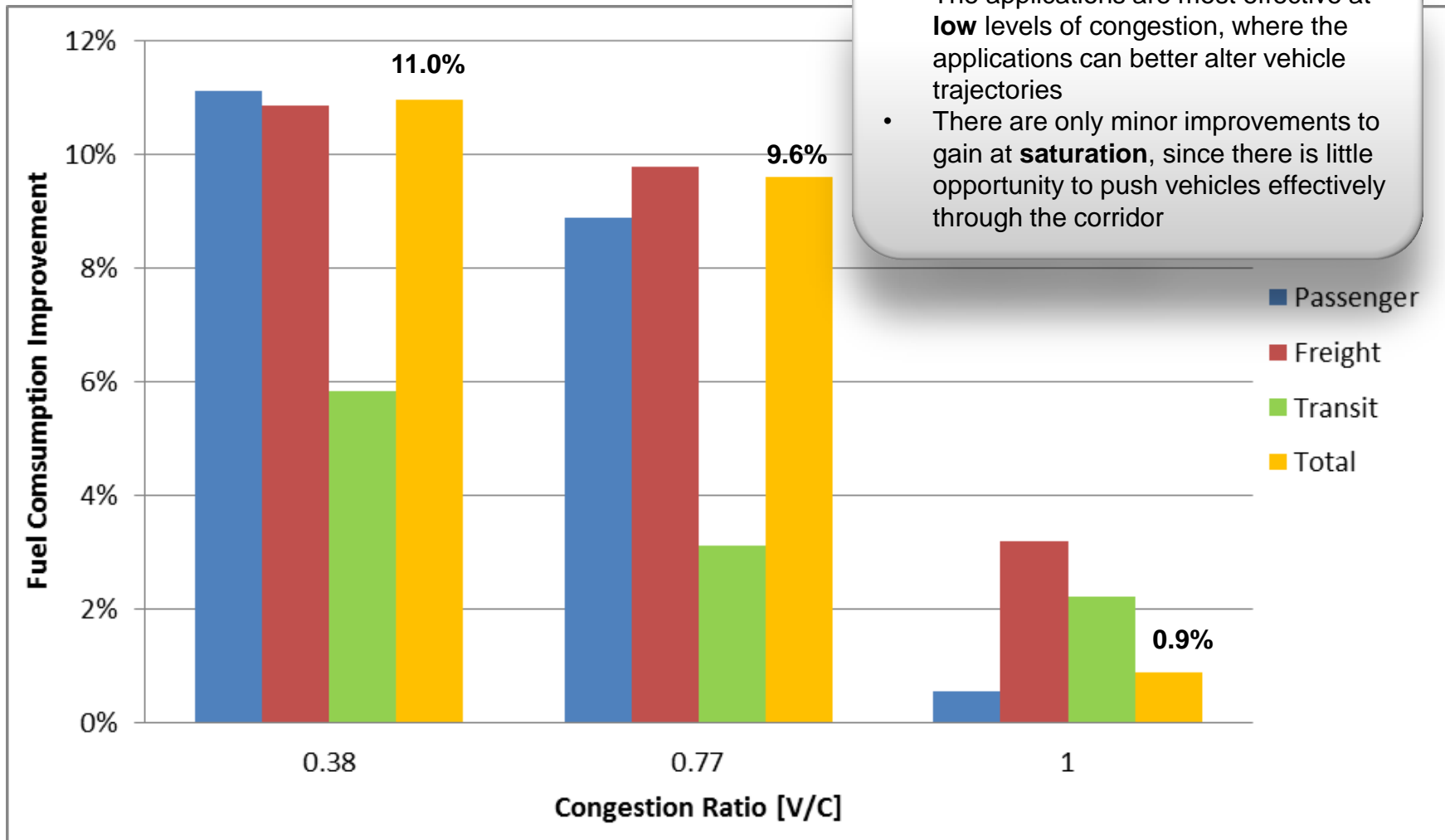
Freight Improvements - Connected vs. Not-Connected



- Non-connected vehicles receive incidental improvements from the applications benefitting from additional green time and improved speed profiles on the mainline
- This occurs at both low and high connected vehicle penetration rates



# Impact of Demand/Congestion



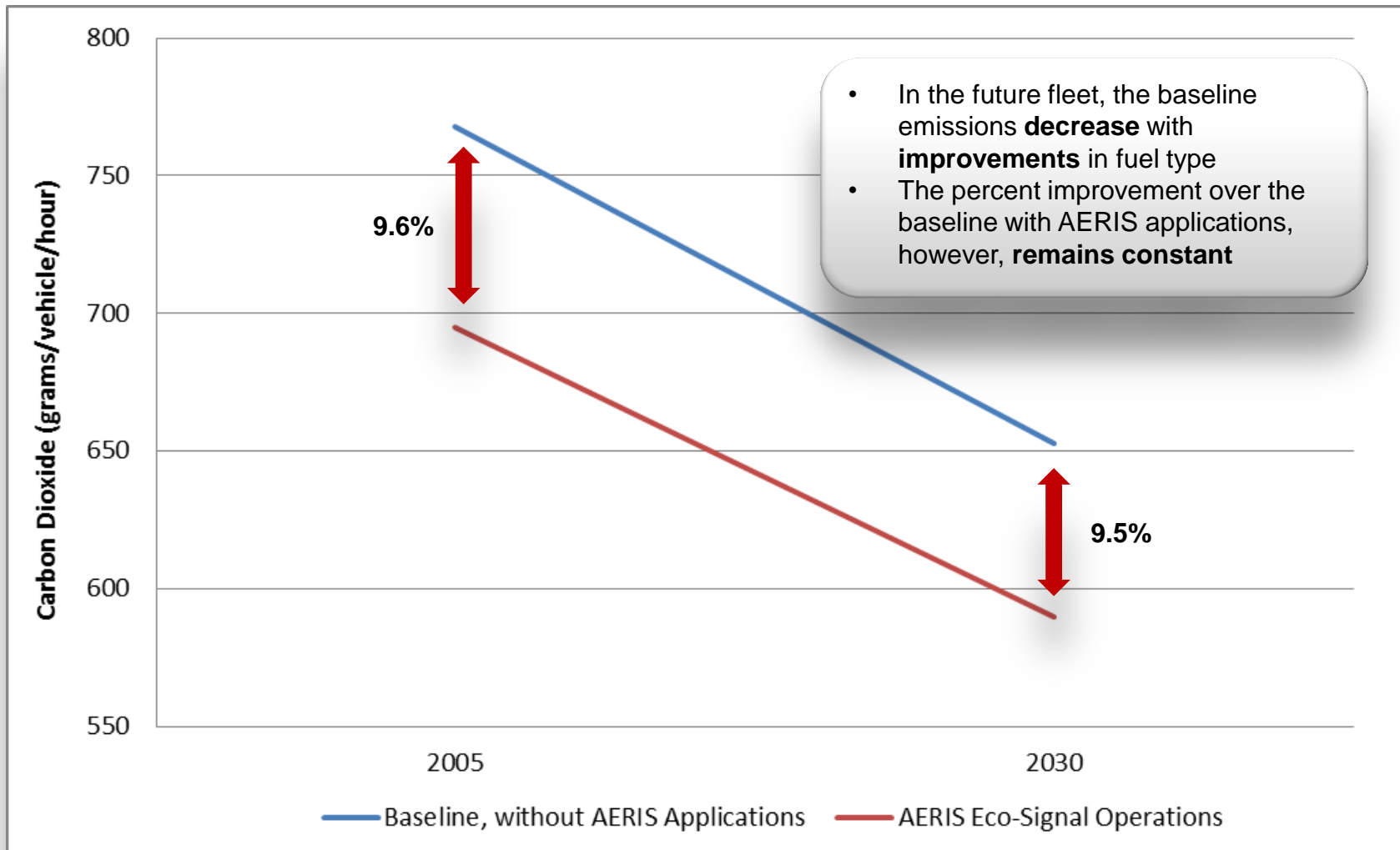
# Future Fleet Impact Estimation

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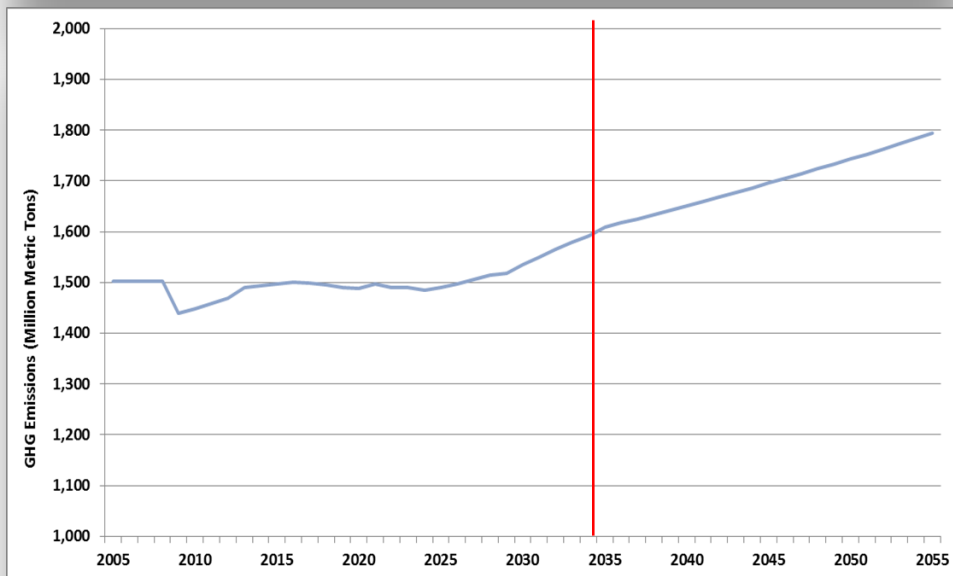
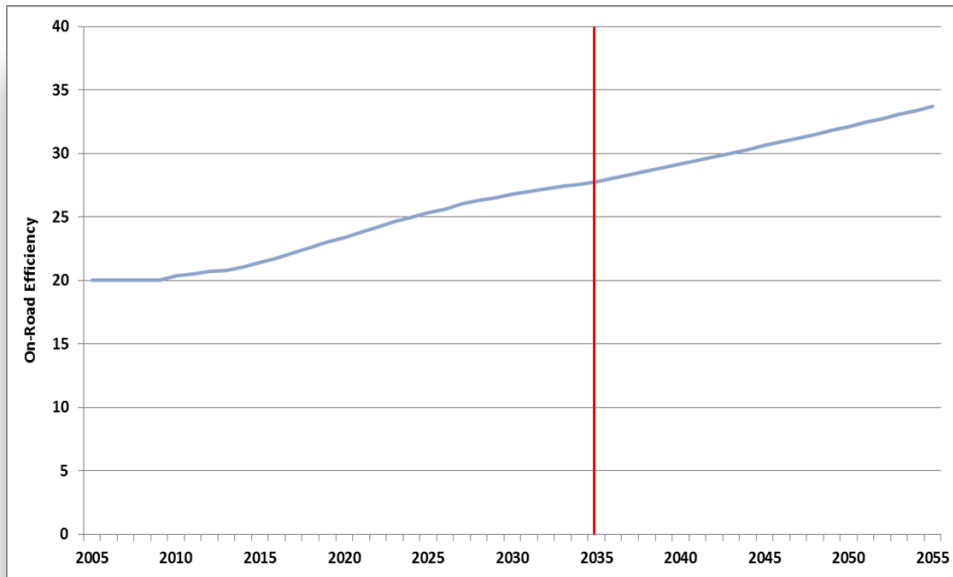
- With estimated improvements in fuel efficiency and increased penetration of hybrid/electric vehicles, it was important to see if similar results could be obtained in future fleets:
  - The 2011 California Emissions Factor (EMFAC2011) model was used to estimate the composition of the **2030 fleet mix** for age and fuel type distribution
  - The baseline model was run for the 2030 fleet mix to determine the **baseline changes** in emissions in the future
  - Then the future 2030 fleet mix was used with the **combined Eco-Signal Operations applications** to determine the impact



# Difference in Impact between 2005 and 2030 Fleet Mixes



# Why Care about Future Impacts?



- While fuel efficiency is predicted to improve in future years, predicted future VMT **will actually increase** overall emission volumes
- Modeling of the Eco-Signal Operations applications show that future percentage improvements are **similar**
- The applications will help **mitigate** future predicted increases in GHG emissions



# Potential User Benefits

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# Estimating Potential Benefits to Users



AERIS applications help drivers reduce their carbon footprint and reduce their fuel consumption. **Drivers help the environment and save money at the pump.**



Fleet operators also benefit from AERIS applications. **Fuel savings help fleet operators save fuel costs resulting in lower operating costs.**



**AERIS applications benefit cities, helping reduce emissions and improving the city's air quality.** AERIS applications also help reduce congestion and support sustainable transportation solutions.

- Assuming a corridor with average traffic congestion
  - Modeling results indicate the following benefits:
    - **Light vehicles: 9.6% reductions in fuel consumption**
    - **Freight: 9.8% reductions in fuel consumption**
    - **Transit: 3.1% reductions in fuel consumption**
  - Gasoline costs:
    - \$3.67/gallon (light vehicle and SUV)
    - \$3.95/gallon for diesel (trucks)
    - \$3.00/gallon estimated for mix of CNG and diesel fleets (transit)
  - Average miles traveled on arterials:
    - Light duty vehicle and SUVs: 8,250 miles
    - City delivery truck: 30,000 miles
    - Transit: 44,600 miles
  - Estimated Benefits
    - Light Vehicle, 23 MPG ~ **\$126 per year**
    - Sport Utility Vehicle (SUV), 17 MPG ~ **\$170 per year**
    - City Delivery Fleet (1,000 vehicles), 7.3 MPG ~ **\$1.6M per year**
    - Transit Fleet (1,000 vehicles), 4 MPG ~ **\$918,000 per year**





# **Lessons Learned and Opportunities for Future Research**

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# Lessons Learned

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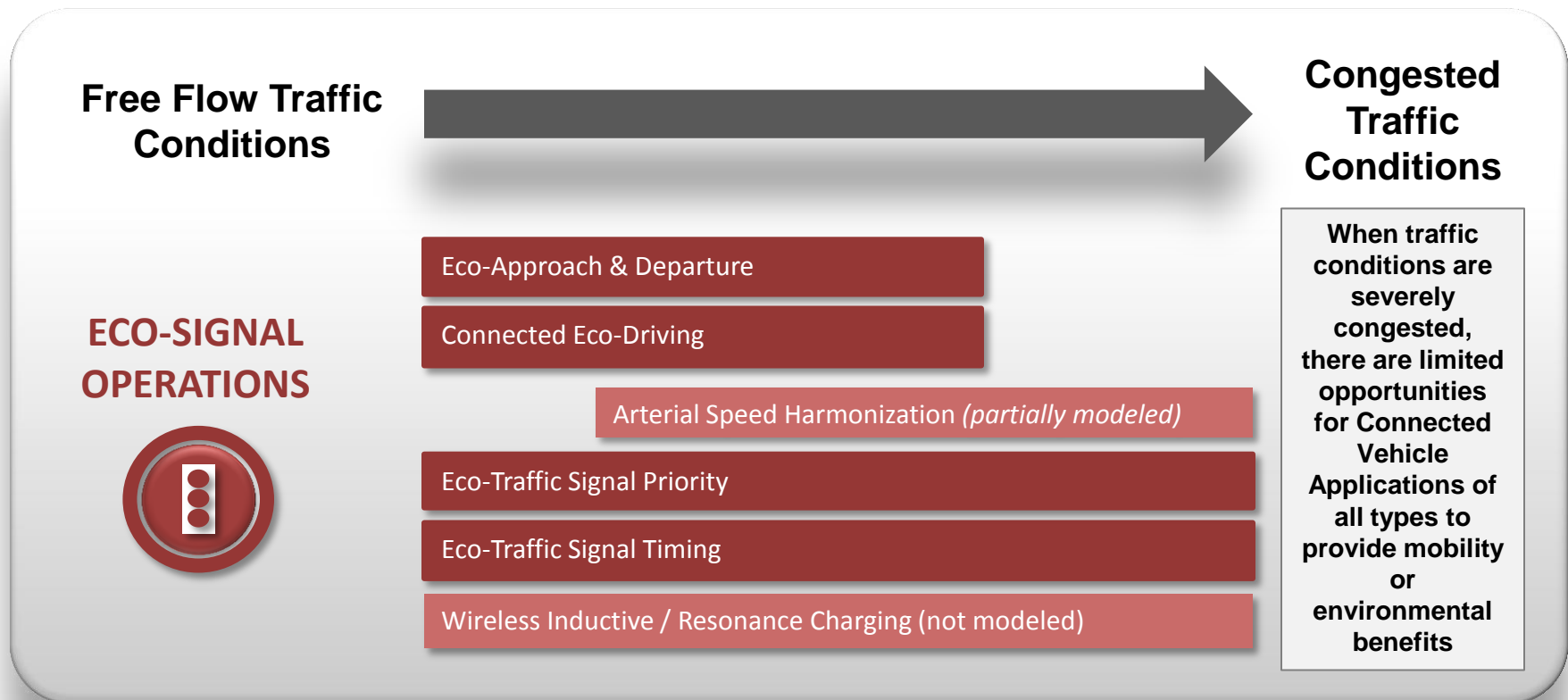
*With the results of the combined modeling, we can answer some of the questions we hypothesized before the analyses:*

- The combined applications may not be additive of the results of the individual modeling results, but modeling showed that **none of the applications conflicted with each other**
- Individual application gains of 2% to 5% are good, but when combined, the **total impact** is quite significant in terms of fuel savings and emission reductions (9.6% benefits at full connected vehicle penetration)
- Noticeable benefits can be gained **even at low** connected vehicle OBE penetration rates, which is promising for early adopters of connected vehicle technologies and AERIS applications
- Environmental benefits **increase with increasing levels** of OBE penetration rate for all individual applications, as well as when combined



# Lessons Learned

- Applications work better in **lower congestion**, since there is more opportunity for vehicles to modify their trajectory and to improve signal timings



# Lessons Learned

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- Non-connected vehicles receive **incidental benefits** from improved signal timings, granted signal priorities, and speed advice meant for the connected vehicles
- Most of the applications have corresponding improvements in **mobility** measures, such as delay and travel time
- Communication delay did not have a noticeable impact on the results, indicating the opportunity for **great flexibility** in wireless communication technology
- Varying the multiple sensitivity parameters during the analyses, such as decision distance and extension maximums, was shown to increase potential benefits, proving the **customizability** of applications to suit location-specific needs



# One Final Thought...

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- Since the El Camino Real corridor was a well-timed corridor, the environmental results gained from the applications are **conservative**
- Many municipalities and regions around the country have sub-optimal optimizations and traffic conditions
- Research has shown that **better benefits** can be obtained in uncoordinated traffic signal systems
- Therefore, there is **potential** to gain greater environmental benefits from the Eco-Signal Operations applications in real-world situations



# Opportunities for Future Research

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- **Compliance rate** could be further investigated to better models the drivers' willingness and ability to follow the speed advice recommendations
- Additional modeling could be considered on different corridor demand configurations (e.g., a corridor with higher demands on the side streets, an urban grid, etc.)
- The resultant signal timings from running the Eco-Approach and Departure and the Eco-Traffic Signal Timing applications **in combination** could be greatly improved if the optimization process included the eco-friendly speed advice to vehicles during the runs
- More **aggressive assumptions** of electric and hybrid fuel vehicles (more aggressive than EMFAC2011) could be considered in future modeling efforts



# Opportunities for Future Research

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- While commercial products do not exist for the Eco-Signal Operations applications (or other connected vehicle applications), the AERIS Program sees opportunities to work with the adopter community to move these concepts toward deployment.
- Future research opportunities include:
  - Continuing to **enhance the underlying algorithms**;
  - Developing **prototypes of the applications** to test their efficacy and usefulness;
  - Working with the adopter community (e.g., state and local DOTs, vehicle OEMS, traffic control industry, etc.) to **pilot AERIS applications in a real-world environment including the USDOT's CV Pilots initiative**; and
  - Transferring benefits and lessons learned to entities likely to deploy the applications.



# Eco-Signal Operations Modeling Team

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- **Booz Allen Hamilton**

- Balaji Yelchuru (Principal Investigator)
- Sean Fitzgerald
- Sudeeksha Murari

- **University of California, Riverside**

- Matt Barth (Principal Investigator)
- Guoyuan Wu (Postdoctoral Fellow)
- Haitao Xia (Graduate Student)

- **University of New South Wales**

- Travis Waller (Principal Investigator)
- Vinayak Dixit
- Kasun Wijayaratna (Graduate Student)
- Tuo Mao (Graduate Student)

- **AERIS Research Team Partners**





# Upcoming AERIS Webinars

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- 2014 AERIS Summer Webinar Series
  - Webinar #2: Preliminary Eco-Lanes Modeling Results  
*Wednesday, July 23rd, 2014 at 1:00 pm EST*
  - Webinar #3: Preliminary Low Emissions Zones Modeling Results  
*Wednesday, August 20th, 2014 at 1:00pm EST*

**Registration:** [www.itsa.org/aerissummer2014](http://www.itsa.org/aerissummer2014)

- For more information on the AERIS Program:  
<http://www.its.dot.gov/aeris/>

